Big Data Optimization for Modern Communication Networks

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The era of 'big data'

The "big data" presents us opportunities:

- Personal advertisement.
- Intelligent social network analysis.
- Smart city development.
- Medical data management.
- Smart grid evolution.
- Geophysics.



Figure: Big data '3V'.

- Big data requires big models and novel methods.
 - Thousands of parameters on TBs of data.
- Big data needs systems built for it.
 - ► Hadoop, Apache Spark, Storm, Yahoo! S4, Parameter sever.

Motivations and Contributions

- New computational mathematical models and methodologies must be explored.
 - Respect the inherent structure of the data. (Sparse, low rank, prior...).
 - Enjoys robustness and scalability.
- Review the parallel and distributed optimization algorithms based on ADMM.
- Investigated the 'big data' optimization methods for modern communication networks.
 - Smart grid security
 - Mobile data traffic management

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Dual Ascent Methods

Consider an optimization problem of the form

$$\min_{\mathbf{x}\in\mathcal{X}} f(\mathbf{x}) \quad \text{s.t.} \quad \mathbf{A}\mathbf{x} = \mathbf{c},$$

- The Lagrangian: $\mathcal{L}(\mathbf{x}, \boldsymbol{\lambda}) = f(\mathbf{x}) + \boldsymbol{\lambda}^{\top} (\mathbf{A}\mathbf{x} \mathbf{c}),$
- Dual function: $g(\lambda) = \inf_{x} \mathcal{L}(\mathbf{x}, \lambda)$,
- Dual Problem: $\max_{\lambda} g(\lambda)$,
- Optimal solution: $\mathbf{x}^* = \arg \min_{\mathbf{x}} \mathcal{L}(\mathbf{x}, \boldsymbol{\lambda}^*)$,

$$\blacktriangleright \text{ Dual Ascent: } \begin{cases} \mathbf{x}^{k+1} = \arg\min_{\mathbf{x}} \mathcal{L}(\mathbf{x}, \boldsymbol{\lambda}^k), \\ \boldsymbol{\lambda}^{k+1} = \boldsymbol{\lambda}^k + \rho^k (\mathbf{A} \mathbf{x}^{k+1} - \mathbf{c}). \end{cases}$$

Require an appropriate step size ρ and assumptions of strong convexity of the objective function f.

Method of Multipliers

Introduce an augmentation $\|\mathbf{A}\mathbf{x} - \mathbf{c}\|_2^2$ to the Lagrangian:

► The Augmented Lagrangian:

$$\mathcal{L}_{\rho}(\mathbf{x}, \boldsymbol{\lambda}) = f(\mathbf{x}) + \boldsymbol{\lambda}^{\top} (\mathbf{A}\mathbf{x} - \mathbf{c}) + \frac{\rho}{2} \|\mathbf{A}\mathbf{x} - \mathbf{c}\|_{2}^{2}$$

► Method of Multipliers:
$$\begin{cases} \mathbf{x}^{k+1} = \arg\min_{\mathbf{x}} \mathcal{L}_{\rho}(\mathbf{x}, \boldsymbol{\lambda}^{k}), \\ \boldsymbol{\lambda}^{k+1} = \boldsymbol{\lambda}^{k} + \rho(\mathbf{A}\mathbf{x}^{k+1} - \mathbf{c}), \end{cases}$$

Pros:

- Stable, robust and fast compare with the dual ascent method.
- No need to tune the parameter ρ during each iteration.

Cons:

• Difficult to decouple and parallelize due to the augmentation $\|\mathbf{A}\mathbf{x} - \mathbf{c}\|_2^2$.

Alternating Direction Method of Multipliers(ADMM)

The general form of ADMM is expressed as

$$\min_{\mathbf{x}_1 \in \mathcal{X}_1, \mathbf{x}_2 \in \mathcal{X}_2} f_1(\mathbf{x}_1) + f_2(\mathbf{x}_2) \quad \text{s.t.} \quad \mathbf{A}_1 \mathbf{x}_1 + \mathbf{A}_2 \mathbf{x}_2 = \mathbf{c}.$$
(1)

The augmented Lagrangian for (1) is

$$egin{aligned} \mathcal{L}_{
ho}(\mathbf{x}_1,\mathbf{x}_2,oldsymbol{\lambda}) &= f_1(\mathbf{x}_1) + f_2(\mathbf{x}_2) + oldsymbol{\lambda}^ op (oldsymbol{A}_1\mathbf{x}_1 + oldsymbol{A}_2\mathbf{x}_2 - oldsymbol{c}) \ &+ rac{
ho}{2} \|oldsymbol{A}_1\mathbf{x}_1 + oldsymbol{A}_2\mathbf{x}_2 - oldsymbol{c}\|_2^2, \end{aligned}$$

A Gauss-Seidel iterations of \mathbf{x}_1 and \mathbf{x}_2 as follows

$$\left\{ \begin{array}{l} \mathbf{x}_1^{k+1} = \arg\min_{\mathbf{x}_1} \mathcal{L}_{\rho}(\mathbf{x}_1, \mathbf{x}_2^k, \boldsymbol{\lambda}^k), \\ \mathbf{x}_2^{k+1} = \arg\min_{\mathbf{x}_2} \mathcal{L}_{\rho}(\mathbf{x}_1^{k+1}, \mathbf{x}_2, \boldsymbol{\lambda}^k), \\ \boldsymbol{\lambda}^{k+1} = \boldsymbol{\lambda}^k + \rho(\mathbf{A}_1 \mathbf{x}_1^{k+1} + \mathbf{A}_2 \mathbf{x}_2^{k+1} - \mathbf{c}). \end{array} \right.$$

Global convergence for convex optimization with a convergence rate O(1/k)

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Direct Extension

Consider the following convex optimization problem

$$\min_{\mathbf{x}_{1},\mathbf{x}_{2},...,\mathbf{x}_{N}} f(\mathbf{x}) = f_{i}(\mathbf{x}_{i}) + \ldots + f_{N}(\mathbf{x}_{N}),$$

s.t. $\mathbf{A}_{i}\mathbf{x}_{i} + \ldots + \mathbf{A}_{N}\mathbf{x}_{N} = \mathbf{c},$
 $\mathbf{x}_{i} \in \mathcal{X}_{i}, \quad i = 1, \ldots, N.$ (2)

The augmented Lagrangian:

$$\mathcal{L}_{\rho}(\{\mathbf{x}_i\}_{i=1}^N, \boldsymbol{\lambda}) = \sum_{i=1}^N f_i(\mathbf{x}_i) + \boldsymbol{\lambda}^{\top} (\sum_{i=1}^N \mathbf{A}_i \mathbf{x}_i - \mathbf{c}) + \frac{\rho}{2} \|\sum_{i=1}^N \mathbf{A}_i \mathbf{x}_i - \mathbf{c}\|_2^2$$

Gauss-Seidel Multi-block ADMM:

$$\begin{cases} \mathbf{x}_i = \arg\min_{\mathbf{x}_i} \mathcal{L}_{\rho}(\{\mathbf{x}_j^{k+1}\}_{j < i}, \mathbf{x}_i, \{\mathbf{x}_j^k\}_{j > i}, \boldsymbol{\lambda}^k), & i = 1, \dots, N. \\ \boldsymbol{\lambda}^{k+1} = \boldsymbol{\lambda}^k + \rho(\sum_{i=1}^N \mathbf{A}_i \mathbf{x}_i^{k+1} - \mathbf{c}). \end{cases}$$

Gauss-Seidel mulit-block ADMM is not necessarily convergent

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Variable Splitting Multi-block ADMM

Reformulate (2) by introducing auxiliary variable z

$$\min_{\mathbf{x},\mathbf{z}} \quad \sum_{i=1}^{N} f_i(\mathbf{x}_i) + I_{\mathcal{Z}}(\mathbf{z}) \quad \text{s.t.} \quad \mathbf{A}_i \mathbf{x}_i + \mathbf{z}_i = \frac{\mathbf{c}}{N}, \quad i = 1, \dots, N,$$

where $\mathcal{Z} = \{ \mathbf{z} | \sum_{i=1}^{N} \mathbf{z}_i = 0 \}$, $I_{\mathcal{Z}}(\mathbf{z})$ is the indicator function.

The augmented Lagrangian

$$\mathcal{L}_{\rho} = \sum_{i=1}^{N} f_i(\mathbf{x}_i) + I_{\mathcal{Z}}(\mathbf{z}) + \sum_{i=1}^{N} \lambda_i^{\top} (\mathbf{A}_i \mathbf{x}_i + \mathbf{z}_i - \frac{\mathbf{c}}{N}) + \frac{\rho}{2} \sum_{i=1}^{N} \|\mathbf{A}_i \mathbf{x}_i + \mathbf{z}_i - \frac{\mathbf{c}}{N}\|_2^2.$$

Variable splitting multi-block ADMM

$$\begin{cases} \mathbf{x}_{i}^{k+1} = \arg\min_{\mathbf{x}_{i}} \mathcal{L}_{\rho}(\mathbf{x}_{i}, \mathbf{z}_{i}^{k}, \lambda_{i}^{k}), \\ \mathbf{z}_{i}^{k+1} = \arg\min_{\mathbf{z}_{i}} \mathcal{L}_{\rho}(\mathbf{x}_{i}^{k+1}, \mathbf{z}_{i}, \lambda_{i}^{k}), \quad \forall i = 1, \dots, N, \\ \lambda_{i}^{k+1} = \lambda_{i}^{k} + \rho(\mathbf{A}_{i}\mathbf{x}_{i} + \mathbf{z}_{i} - \frac{\mathbf{c}}{N}). \end{cases}$$

Converge as two-block setting, but the number of variables and constraints will increase substantially when N is large.

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Proximal Jacobian ADMM

Recall the augmented Lagrangian:

$$\mathcal{L}_{\rho}(\{\mathbf{x}_i\}_{i=1}^N, \boldsymbol{\lambda}) = \sum_{i=1}^N f_i(\mathbf{x}_i) + \boldsymbol{\lambda}^{\top}(\sum_{i=1}^N \mathbf{A}_i \mathbf{x}_i - \mathbf{c}) + \frac{\rho}{2} \|\sum_{i=1}^N \mathbf{A}_i \mathbf{x}_i - \mathbf{c}\|_2^2$$

A proximal term is added to the augmented Lagrangian, and the update of \mathbf{x}_i is performed concurrently:

$$\begin{cases} \mathbf{x}_{i}^{k+1} = \arg\min_{\mathbf{x}_{i}} \mathcal{L}_{\rho}(\mathbf{x}_{i}, \{\mathbf{x}_{j}^{k}\}_{j \neq i}, \boldsymbol{\lambda}^{k}) + \frac{1}{2} \|\mathbf{x}_{i} - \mathbf{x}_{i}^{k}\|_{\mathbf{P}_{i}}^{2}, \\ \boldsymbol{\lambda}^{k+1} = \boldsymbol{\lambda}^{k} + \gamma \rho(\sum_{i=1}^{N} \mathbf{A}_{i} \mathbf{x}_{i}^{k+1} - \mathbf{c}), \qquad \forall i = 1, \dots, N. \end{cases}$$

where $\|\mathbf{x}_i\|_{\mathbf{P}_i}^2 = \mathbf{x}_i^\top \mathbf{P}_i \mathbf{x}_i$ for some symmetric and positive semi-definite matrix $\mathbf{P}_i \succeq 0$. The involvement of the proximal term

- Make subproblem of x_i strictly or strongly convex
- Ensure the convergence. Easier to solve.

Recap: From Dual Ascent to Multi-block ADMM



- 1. Stability and robustness are the utmost concern for an optimization algorithm.
- 2. Should better be distributed and parallel.
- 3. If possible, we want it converge fast.

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Smart Grid 'Big Data'



The anticipated smart grid data deluge:

- 1. The deployment of phasor measurement units for future North American power grid will generate 4.15 TB data per day.
- 61.8 million smart meters are deployed in the U.S. by the end of 2013. Every one million users will produce 27.3TB per year.

Blackout

- Increasing integration between cyber operations and physical infrastructures for generation, transmission, and distribution control.
- The security and reliability are not guaranteed



Figure: 2003 blackout

(3)

Contingency Analysis

Simple example



- 1. Assume line 1-2 is disconnected.
- 2. Generators A and B cannot change productions quickly.
- 3. The flows over other lines would increase.
- 4. Trigger cascading failure.

Security Constrained Optimal Power Flow (SCOPF)

SCOPF: Minimizing the cost of system operation while satisfying a set of postulated contingency constraints.

$$\begin{split} & \min_{\{\mathbf{x}^c\}_0^C; \{\mathbf{u}^c\}_0^C} \quad f^0(\mathbf{u}^0) \quad \text{scheduling objective} \\ & \text{s.t.} \quad \mathbf{g}^0(\mathbf{x}^0, \mathbf{u}^0) = 0, \text{power flow equations} \\ & \mathbf{h}^0(\mathbf{x}^0, \mathbf{u}^0) \leq 0, \text{operating limits for base case} \\ & \mathbf{g}^c(\mathbf{x}^c, \mathbf{u}^c) = 0, \text{power flow equations} \\ & \mathbf{h}^c(\mathbf{x}^c, \mathbf{u}^c) \leq 0, \text{operating limits for contingency k} \\ & \|\mathbf{u}^0 - \mathbf{u}^c\|^2 \leq \mathbf{\Delta}_c, c = 1, \dots, C, \text{security constrains} \end{split}$$

Challenges:

- 1. Number of constraints is prohibitive.
- 2. How to find the best operating point with a scalable algorithm?

DC Approximation

Power flow equations:

$$P_i = \sum_{k=1}^{N} |V_i| |V_k| (G_{ik} \cos \theta_{ik} + B_{ik} \sin \theta_{ik}),$$
$$Q_i = \sum_{k=1}^{N} |V_i| |V_k| (G_{ik} \sin \theta_{ik} - B_{ik} \cos \theta_{ik}),$$

where G_{ik} and B_{ik} are the real and imaginary part of $(i, k)^{th}$ element of the bus admittance matrix. DC power flow approximation:

- 1. Neglect the reactive power.
- 2. Neglect resistance of the branches.
- 3. Assume all voltage magnitudes = 1.0 p.u.
- 4. Assume all angles are small.

DC SCOPF

'N-1' contingency, corrective setting:

$$\begin{split} \min_{\{\theta^c\}_{c=0}^C; \{\mathbf{P}^{g,c}\}_{c=0}^C} & \sum_{i\in\mathcal{G}} f_i^g(\mathbf{P}_i^{g,0}) \\ \text{subject to} & \mathbf{B}_{bus}^0 \theta^0 + \mathbf{P}^{d,0} - \mathbf{A}^{g,0} \mathbf{P}^{g,0} = 0, \\ & \mathbf{B}_{bus}^c \theta^c + \mathbf{P}^{d,c} - \mathbf{A}^{g,c} \mathbf{P}^{g,c} = 0, \\ & |\mathbf{B}_f^c \theta^0| - \mathbf{F}_{max} \leq 0, \\ & |\mathbf{B}_f^c \theta^c| - \mathbf{F}_{max} \leq 0, \\ & \frac{\mathbf{P}^{g,0}}{\mathbf{P}^{g,0}} \leq \mathbf{P}^{g,0} \leq \overline{\mathbf{P}^{g,0}}, \\ & \frac{\mathbf{P}^{g,c}}{\mathbf{P}^{g,c}} \leq \mathbf{P}^{g,c} \leq \overline{\mathbf{P}^{g,c}}, \\ & |\mathbf{P}^{g,0} - \mathbf{P}^{g,c}| \leq \mathbf{\Delta}_c, \\ & i \in \mathcal{G}, \quad c = 1, \dots, C, \end{split}$$

where \mathbf{B}_{bus} and \mathbf{B}_{f} can be modified from the bus admittance matrix \mathbf{Y}_{bus} . $\mathbf{A}^{g,c}$ is the generator connection matrix.

A Distributed Approach by ADMM

Introduce a slack variable \mathbf{p}^{c} to rewrite $|\mathbf{P}^{g,0} - \mathbf{P}^{g,c}| \leq \mathbf{\Delta}_{c}$ as:

$$\mathbf{P}^{g,0} - \mathbf{P}^{g,c} + \mathbf{p}^{c} = \mathbf{\Delta}_{c}$$
(3)
$$0 \le \mathbf{p}^{c} \le 2\mathbf{\Delta}_{c}, \quad c = 1, \dots, C.$$

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The partial scaled augmented Lagrangian associated with (3) can be calculated with follows

$$\mathcal{L}_{\rho}(\{\mathbf{P}^{g,c}\}_{c=0}^{C}; \{\mathbf{p}^{c}\}_{c=1}^{C}; \{\mu^{c}\}_{c=1}^{C})$$

= $\sum_{i \in \mathcal{G}} f_{i}^{g}(\mathbf{P}_{i}^{g,0}) + \sum_{c=1}^{C} \frac{\rho^{c}}{2} \|\mathbf{P}^{g,0} - \mathbf{P}^{g,c} + \mathbf{p}^{c} - \mathbf{\Delta}_{c} + \mu^{c}\|_{2}^{2}.$

Iterate till convergence

- 1. Update $\{\mathbf{P}^{g,0}\}$.
- 2. Update $\{\mathbf{P}^{g,c}, \mathbf{p}^{c}\}$.
- 3. Update dual variable μ^c .

A Distributed Approach by ADMM (cont.)

The update for base case (Modified OPF problem):

$$\begin{aligned} \mathbf{P}^{g,0}[k+1] &= \arg\min_{\mathbf{P}^{g,0}} \sum_{i \in \mathcal{G}} f_i^g(\mathbf{P}_i^{g,0}) \\ &+ \sum_{c=1}^C \frac{\rho^c}{2} \|\mathbf{P}^{g,0} - \mathbf{P}^{g,c}[k] + \mathbf{p}^c[k] - \mathbf{\Delta}_c + \mu^c[k] \|_2^2, \end{aligned}$$

The update for contingency case c

$$\mathbf{P}^{g,c}[k+1] = \operatorname*{arg\,min}_{\mathbf{P}^{g,c},\mathbf{p}^c} \frac{\rho^c}{2} \|\mathbf{P}^{g,0}[k+1] - \mathbf{P}^{g,c} + \mathbf{p}^c - \mathbf{\Delta}_c + \boldsymbol{\mu}^c[k]\|_2^2,$$

The scaled dual variable is updated by:

$$\mu^{c}[k+1] = \mu^{c}[k] + \mathbf{P}^{g,0}[k+1] - \mathbf{P}^{g,c}[k+1] + \mathbf{p}^{c}[k+1] - \mathbf{\Delta}_{c}.$$

Distributed Implementation



Figure: Distributed Implementation.

- 1. On multi-core machine.
- 2. High performance computer cluster using MPI (message passing interface).
- 3. On cloud using Hadoop or Apache Spark.

Numerical Results

Evaluation setup: Modified data of IEEE 57 bus, IEEE 118 bus and IEEE 300 bus generated by MATPOWER



Figure: Convergence performance.

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Numerical Results (cont.)

Using the Matlab distributed and parallel toolbox, Subproblems are solved by CVX.



Figure: Computing time for IEEE 57 bus.

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Global Mobile Data Traffic



Figure: The global mobile data traffic forecast by region.

- Expected to reach 15.9 EB per month by 2018.
- A 11-fold increase over 2013.

Mind the Gap



Revenue vs. Traffic Growth

Figure: Revenue & traffic gap. Source:radisys.com

The sheer volume of the mobile 'big data' traffic far exceeds

- The growth in service revenues.
- The budgets required to address the new demands.

Mobile Data Offloading



- Mobile data offloading: Offload traffic from cellular networks to alternate wireless technologies.
- Software defined network (SDN) at the edge: Dynamically route the traffic in a mobile network.

Mobile Data Offloading in SDN

Consider a mobile network

- ▶ A BS $b \in \{1, ..., B\}$ serves a group of mobile users.
- ▶ An AP $a \in \{1, ..., A\}$ provides bandwidth for data offloading.
- ▶ $\mathbf{x}_b = [x_{b1}, \dots, x_{bA}]^\top$ represent the offloaded traffic of BS b.
 - x_{ba} denotes the data of BS *b* offloaded through AP *a*.
- ► BS b's utility: U_b(x_b). Non-decreasing, non-negative and concave.
- $\mathbf{y}_a = [y_{a1}, \dots, y_{aB}]^\top$ represents the admitted traffic of AP a
 - y_{ab} represents the admitted data traffic from BS b.
- ► AP a's cost: L_a(y_a). Non-decreasing, non-negative and convex.
- ▶ Feasible mobile data offloading decision: $x_{ba} = y_{ab}$, $\forall a$ and $\forall b$.

Mobile Data Offloading in SDN (Cont.)

- Utility of base stations: $\sum_{b=1}^{B} U_b(\mathbf{x}_b)$.
- Cost of access points: $\sum_{a=1}^{A} L_a(\mathbf{y}_a)$.
- ► Total revenue: $\sum_{b=1}^{B} U_b(\mathbf{x}_b) \sum_{a=1}^{A} L_a(\mathbf{y}_a)$.
- Equivalent revenue maximization problem:

$$\begin{array}{ll} \min_{\{\mathbf{x}_1,\ldots,\mathbf{x}_B\},\{\mathbf{y}_1,\ldots,\mathbf{y}_A\}} & \sum_{a=1}^A L_a(\mathbf{y}_a) - \sum_{b=1}^B U_b(\mathbf{x}_b), & \text{Service revenue} \\ \text{s.t} & \sum_{b=1}^B y_{ab} \leq C_a, & \forall a, & \text{Capacity constraint} \\ & x_{ba} = y_{ab}. & \forall a, b & \text{Consensus} \end{array}$$

Challenges

- Privacy preserving: Utility functions at BSs and cost functions at APs should be kept private.
 - How to address the information asymmetry?
- Concurrent update: The updating process at the BSs and APs should be performed concurrently.
 - How to get concurrency?
- Scalability: The operations at the SDN controller should be simple to alleviate the computation burden.

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How to design a scalable scheme?

Proximal Jacobian ADMM

The Lagrangian function

$$\mathcal{L}_{\rho}(\mathbf{x}, \mathbf{y}, \boldsymbol{\lambda}) = \sum_{a=1}^{A} L_{a}(\mathbf{y}_{a}) - \sum_{b=1}^{B} U_{b}(\mathbf{x}_{b}) + \sum_{a=1}^{A} \sum_{b=1}^{B} \lambda_{ab}(x_{ba} - y_{ab}) + \frac{\rho}{2} \sum_{a=1}^{A} \sum_{b=1}^{B} \|x_{ba} - y_{ab}\|_{2}^{2}$$

Base Station Update:

$$\mathbf{x}_b^{k+1} = \operatorname*{arg\,min}_{\mathbf{x}_b} - U_b(\mathbf{x}_b) + \frac{\rho}{2} \sum_{a=1}^A \|x_{ba} - y_{ab}^k + \frac{\lambda_{ab}^k}{\rho}\|_2^2 + \frac{1}{2} \|\mathbf{x}_b - \mathbf{x}_b^k\|_{\mathbf{P}_i}^2.$$

Access Point Update:

$$\begin{split} \mathbf{y}_{a}^{k+1} &= \arg\min_{\mathbf{y}_{b}}(\mathcal{L}_{a}(\mathbf{y}_{a}) + \frac{\rho}{2}\sum_{b=1}^{B}\|y_{ab} - x_{ba}^{k} - \frac{\lambda_{ab}^{k}}{\rho}\|_{2}^{2} + \frac{1}{2}\|\mathbf{y}_{a} - \mathbf{y}_{a}^{k}\|_{\mathbf{P}_{i}}^{2}),\\ \text{s.t} \quad \sum_{b=1}^{B}y_{ab} \leq C_{a}. \end{split}$$

SDN Controller Update:

$$\lambda_{ab}^{k+1} = \lambda_{ab}^{k} + \gamma \rho \sum_{b=1}^{B} \sum_{a=1}^{A} (x_{ba}^{k+1} - y_{ab}^{k+1}).$$

Distributed Update Scheme



1 Gather: BSs and APs concurrently update x and y, which are gathered by controller.

(2) Scatter: Controller simply updates λ , which are scattered to BSs and APs

Figure: Distritbuted update scheme

Iterative gather-scatter scheme (Map-reduce).

► Signaling:
$$p_{ab}^k = (y_{ab}^k - \frac{\lambda_{ab}^k}{\rho}), q_{ba}^k = (x_{ba}^k + \frac{\lambda_{ab}^k}{\rho})$$

Numerical Results

Evaluation setup: B = 5 base stations and $A = \{5, 10\}$ access points. $C_a = 10Mbps$



Figure: Convergence performance

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Numerical Results(Cont.)

Total market gap: $\sum_{a=1}^{A} \sum_{b=1}^{B} (x_{ba} - y_{ab})$



Figure: Offloading gap

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Scalable service management in mobile cloud computing



Figure: An illustration of mobile cloud computing infrastructure.

Sparse optimization for false data injection attacks detection

 \boldsymbol{Z}_0 is the normal temporal state measurement, \boldsymbol{A} is the sparse attack matrix.

$$\min_{\mathbf{Z}_{0},\mathbf{A}} \|\mathbf{Z}_{0}\|_{*} + \lambda \|\mathbf{A}\|_{1}, \quad s.t. \quad \mathbf{Z}_{a} = \mathbf{Z}_{0} + \mathbf{A},$$
(4)

where

▶ || • ||_{*}: nuclear norm. Sum of singular values of a matrix.
 ▶ || • ||₁: *l*₁*norm*. Sum of absolute values of matrix entries.



Figure: Temporal measurements illustration.

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Distributed State Estimation

A fully distributed Gauss-Newton method for state estimation in power system.

$$\min_{\mathbf{x}_i \dots \mathbf{x}_N} \quad f(\mathbf{x}) = \sum_{i=1}^N (\mathbf{z}_i - \mathbf{h}_i(\mathbf{x}_i))^\top \mathbf{R}_i^{-1}(\mathbf{z}_i - \mathbf{h}_i(\mathbf{x}_i)),$$

s.t. $\mathbf{x}_i = \dots = \mathbf{x}_N,$



Smart City

Air quality monitoring using big data techniques.





Figure: Taxi route.

Figure: Air monitoring map

- Ultra fine particles and PM2.5 monitoring.
- Taxi-carried air monitoring sensor.
- ► How to infer the air quality index spatially and temporally?

Smart Meter Data Clustering

From smart meter data, try to tell users usage behaviors

- 1. Housewives?
- 2. Commute workers?
- 3. Ph.D students?





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- A brief review of the alternating direction method of multipliers.
- Zoomed in two applications of big data optimization in modern communication networks.
 - Security constrained optimal power flow in smart grid.
 - Data offloading in software defined networks.
- Effective management and processing of 'big data' has the potential to significantly improve network security and management efficiency.

Awards and Research Summary

Adwards:

Candidate for excellent overseas Chinese Ph.D. student.

Book Chapter:

L. Liu, Z. Han, S. Cui, and V. H. Poor, "Big Data Processing for Smart Grid Security," Big Data over Networks, *Cambridge University Press*, edited by A. Hero, J. Moura, T. Luo, and S. Cui.

Journal:

- L. Liu, M. Esmalifalak, Q. Ding, V. A. Emesih, and Z. Han, "Detecting False Data Injection Attacks on Power Gird by Sparse Optimization," *IEEE Transactions on Smart Grid*, vol. 5, no. 2, pp. 612-621, Mar. 2014.
- M. Esmalifalak, L. Liu, N. Nguyen, R. Zheng, and Z. Han, "Detecting Stealthy False Data Injection Using Machine Learning in Smart Grid," to appear IEEE Systems Journal.
- L. Liu, D. Niyato, P. Wang, and Z. Han, "Scalable Mobile Cloud Services Management with Stochastic Wireless Link Latency," submitted to IEEE Transaction on Mobile Computing.
- L. Liu, A. Khodaei, W. Yin, and Z. Han, "Distribute Approach for Security Constrained Optimal Power Flow with Renewable Generation," submitted to IEEE Transaction on Power System.

Conference:

- L. Liu, A. Khodaei, W. Yin, and Z. Han, "Distribute Parallel Approach for Big Data Scale Optimal Power Flow with Security Constraints," IEEE SmartGridComm, Vancouver, Canada, October 2013.
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Thanks!